

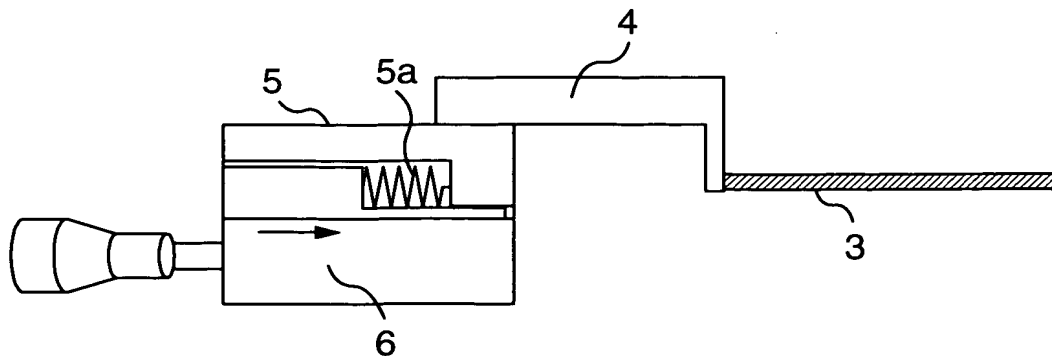
[illegible]

FIG. 3

1) INITIAL STATE

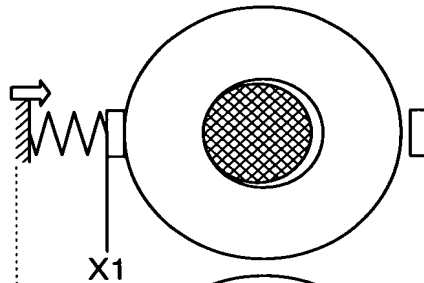
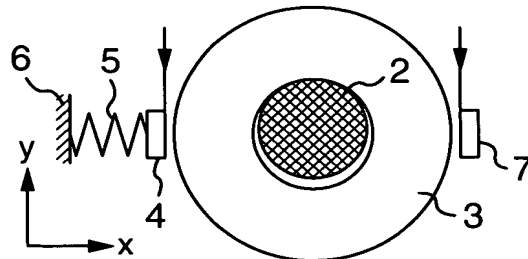
2) COMPLETION OF y-DIRECTION CENTERING

3) APPLICATION OF DISC GRIPPING FORCE

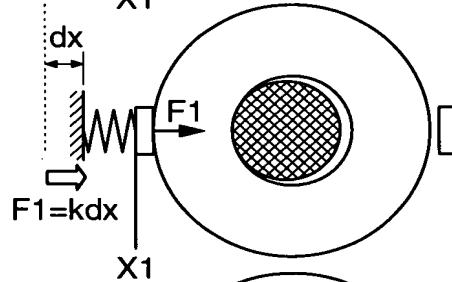
4) MEASUREMENT OF x-DIRECTION GAP

5) COMPLETION OF x-DIRECTION CENTERING

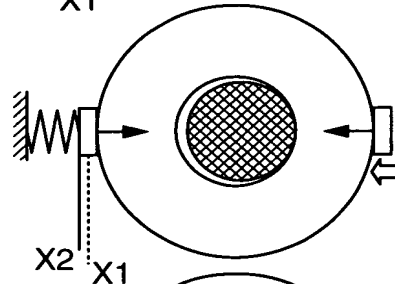
6) MOUNTING CLAMP



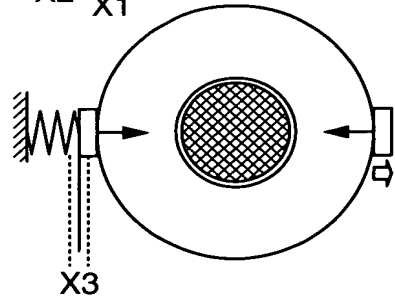
PRESSING UNTIL BEING IN CONTACT WITH HUB AND DETECTING RESISTANCE



FURTHER PRESSING



MOVING IN -x-DIRECTION UNTIL BEING IN CONTACT WITH HUB



RETURN BACK HALF OF GAP $(x_2 - x_1)/2$

FIG. 4

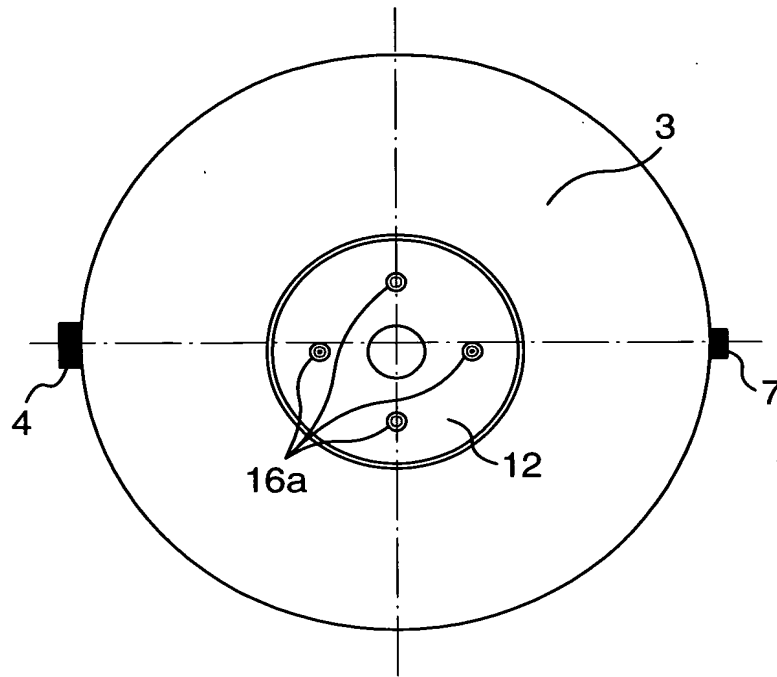
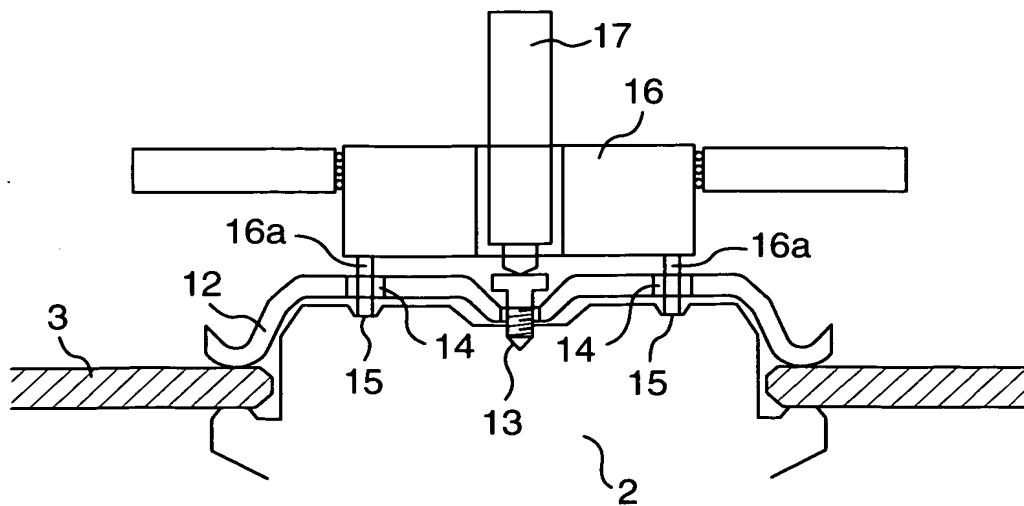


FIG. 5



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FIG. 6

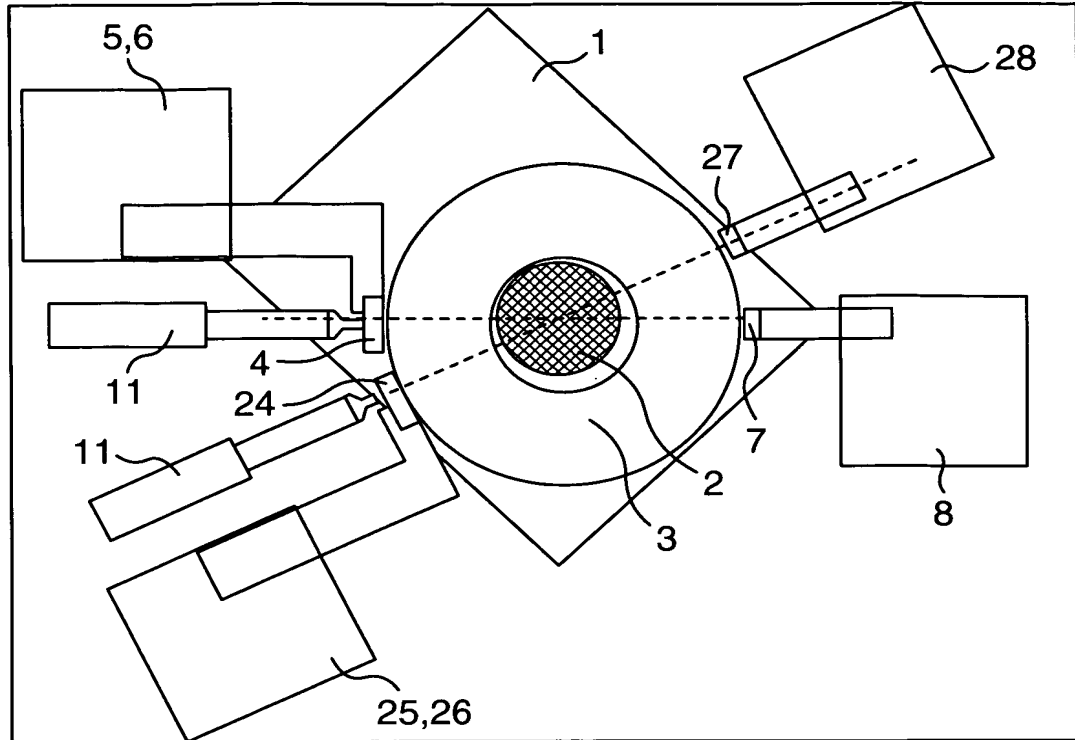


FIG. 7

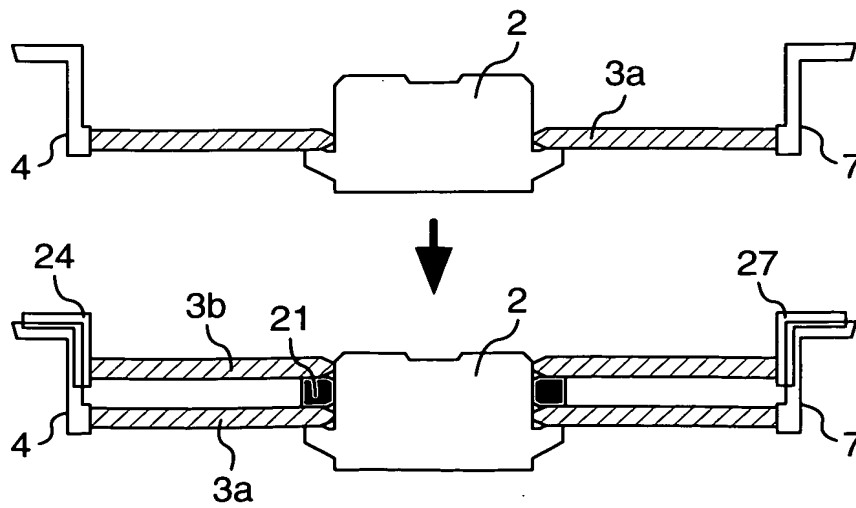


FIG. 8

